Calculating confidence limits for Gain and Phase spectra

for which we need the cumulative Fisher distribution

$$F(n,m,x) \equiv F_x(n,m) = 1 - I_{\frac{m}{m+nx}}(\frac{m}{2},\frac{n}{2})$$

where

$$I_{y}(\mu, \nu) = \frac{B(\mu, \nu, y)}{B(\mu, \nu)}$$

is the normalized incomplete Beta function (IMSL: BETAI, Numerical Recipes also BETAI, but arguments are ordered differently). The inverse of function F will be named f

 $F(n, m, x) = c \iff f(n, m, c) \equiv f_{n,m}(c) = x$

where 0 < c < 1 is a confidence level.

Jenkins and Watts (1968, Chap. 10) show that in smoothed co-spectra the degree of freedom of a line in the power spectrum is n=2 and in the cross-spectrum m>>2, the latter owing to smoothing by windowing (ahum, isn't the power spectrum smoothed the same way? Well, yes, but see J&W chap. 6.4.2). The degrees of freedom *m* of C_{xy} is calculated from J&W (6.4.14) or

$$v = 2 \frac{T}{MI}$$

where

$$I \approx \frac{1}{2M+1} \sum_{i=-M}^{M} w_i^2$$

(J&W use Fourier integrals) is the smoothing effect of a window of 2M < T and *T* the number of samples. Let's call *I* the window's shape factor. An example for the Kaiser-Bessel window with parameter 2.2 and $2M = 2^{12}$, $T = 10 \times 2^{12} = 10 \times 2^$

In http://holt.oso.chalmers.se/hgs/4me/pdgs/KB-wsp.png the black curve is for the Kaiser-Bessel window, the blue one for a rectangular window.

At the end of this document the confidence interval for coherence is given.

in[2]:= betai[na_, nb_, x_] := Beta[x, na, nb] / Beta[na, nb]

In[55]:= fish[na_, nb_, x_] := 1 - betai[nb / 2, na / 2, nb / (nb + na x)]



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For 15 degrees of freedom:
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$\ln[59]:= y = 2 x / n / . Solve[fish[2, n, x] = 0.95, x] / . n \rightarrow 13$

Solve::ifun : Inverse functions are being used by Solve, so

some solutions may not be found; use Reduce for complete solution information. \gg

Out[59]= $\{0.585472\}$

This shows the special case $v_1=2$ of Jenkins and Watts Figure 3.12:

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\begin{split} & \ln[137] = \text{LogLogPlot}[\{x \ /. \ \text{Solve}[\text{fish}[2, n-2, x] = 0.99], x \ /. \ \text{Solve}[\text{fish}[2, n-2, x] = 0.95], \\ & x \ /. \ \text{Solve}[\text{fish}[2, n-2, x] = 0.90]\}, \ \{n, 4, 20\}, \ \text{PlotRange} \rightarrow \{\{4, 20\}, \ \{2, 100\}\}, \\ & \text{PlotLegends} \rightarrow \{\text{"cfd}=99\%\text{"}, \text{"cfd}=95\%\text{"}, \text{"cfd}=90\%\text{"}\}, \ \text{PlotLabel} \rightarrow \text{"f}_{2,\nu_2-2}(cfd)\text{"}, \\ & \text{AxesLabel} \rightarrow \{\text{"}\nu_2\text{"}, \text{""}\}] \end{split}
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General::stop : Further output of Solve::ifun will be suppressed during this calculation. \gg



In[61]:= fishi[f_, na_, nb_] := x /. Solve[fish[na, nb, x] == f]

In[53]:= 2/13 fishi[0.9, 2, 13]

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Out[53]= {0.425103}
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Lower limit for significant coherence k:

In[62]:= Solve[2/13 fishi[0.9, 2, 13] (1 - k) / k == 1, k]

Solve::ratnz : Solve was unable to solve the system with inexact coefficients. The answer was obtained by solving a corresponding exact system and numericizing the result. >>

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{\rm Out} \hbox{\tt [62]=} \ \{ \ \{ \ k \ \rightarrow \ 0 \ . \ 2 \ 9 \ 8 \ 2 \ 9 \ 6 \ \} \ \} \
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 $\ln[110] = k0[c_{, n_{]} := (2 / n) x / ((2 / n) x + 1) / . x \rightarrow fishi[c, 2, n]$

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In[111]:= k0[0.95, 13]
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 $Out[111] = \{0.369273\}$

Show 90%-confidence limit for Gain as a function of coherence κ



Same for phase:

Finally the confidence interval for coherence (we always use the coherence-square albeit denoted by a bare and straight κ):

According to J&W (Chap. 9.2, p. 380) ArcTanh($\sqrt{\kappa}$) is approximately Normal with variance I/(2T). Denote the thus transformed variable with y. Then with the confidence level c and η the inverse of the cumulative Normal distribution

$$\delta y = \pm \eta(\frac{c+1}{2}) \sqrt{\frac{I}{2T}}$$

where I is again the window's shape factor. Then

$$\delta \kappa = \operatorname{Tanh}^2 \left(\delta y \pm \operatorname{ArcTanh} \left[\sqrt{\kappa} \right] \right) - \kappa$$

Proof:

$$ln[142]:= \mathbf{yk}[\mathbf{k}] := \mathbf{ArcTanh}\left[\sqrt{\mathbf{k}}\right]$$

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 \inf[148]:= \{ \text{Solve}[\mathbf{yk}[\mathbf{kk} + \mathbf{u}] = \mathbf{yk}[\mathbf{kk}] + \mathbf{v}, \mathbf{u}], \text{Solve}[\mathbf{yk}[\mathbf{kk} + \mathbf{u}] = \mathbf{yk}[\mathbf{kk}] - \mathbf{v}, \mathbf{u}] \} 
\operatorname{Out}[148]:= \{ \{ \{\mathbf{u} \rightarrow -\mathbf{kk} + \operatorname{Tanh}\left[\mathbf{v} + \operatorname{ArcTanh}\left[\sqrt{\mathbf{kk}}\right]\right]^2 \} \}, \{ \{\mathbf{u} \rightarrow -\mathbf{kk} + \operatorname{Tanh}\left[\mathbf{v} - \operatorname{ArcTanh}\left[\sqrt{\mathbf{kk}}\right]\right]^2 \} \} \}
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